

# SmartAnswer - Domain decomposition for modeling of acoustic liners

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Smart Mitigation of flow-induced Acoustic Radiation and Transmission for reduced Aircraft, surface traNSport, Workplaces and wind enERgy noise



Siemens PLM Software

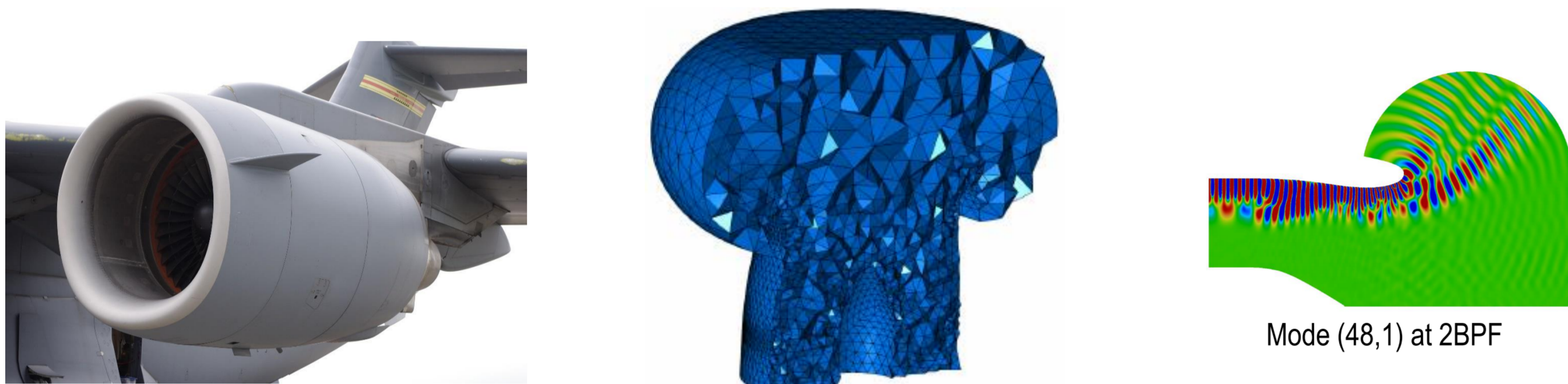


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## Motivation

In modern aircrafts, engine noise is a major source of noise. There is a growing demand for numerical prediction techniques to help finding better designs and improve acoustic performance.

Current numerical models are computationally very intensive.



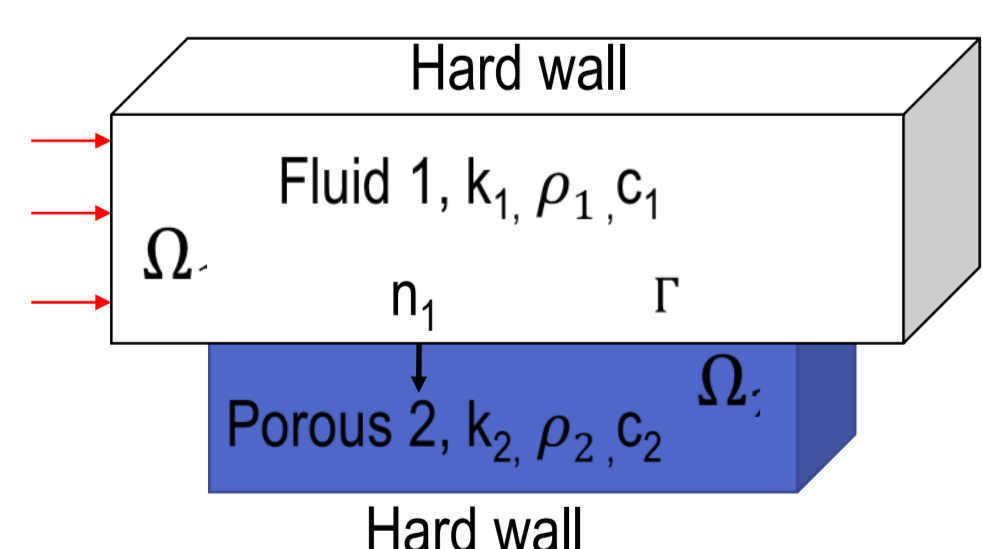
For example, at 2BPF, 3D noise radiation of a given tone in sideline configuration required 5h 30 min [1]. Hundreds of simulations are required to obtain optimal design settings and in particular, **acoustic liner parameters**. The demand for robust, efficient, scalable numerical acoustic methodologies is increasing.

## Main Objective

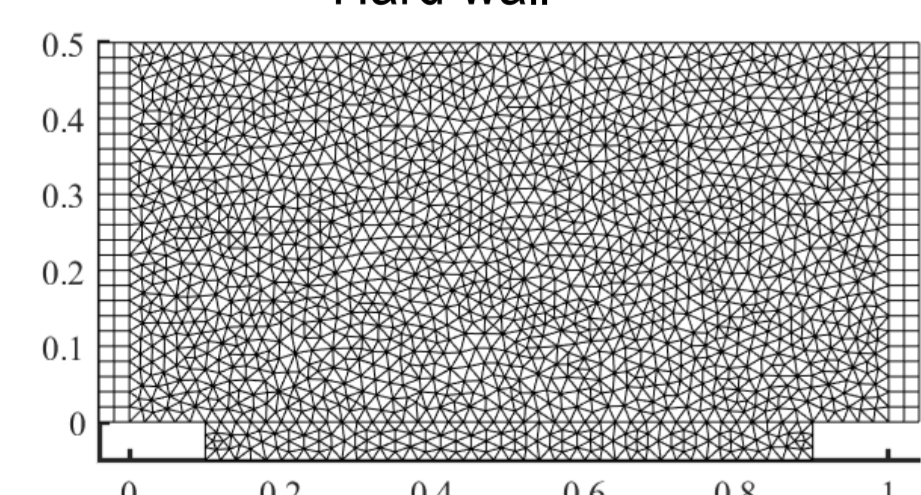
- Domain decomposition methods (DDM) are highly parallel and reduce the computational costs drastically.
- Extension of the non-overlapping domain decomposition methods to liner optimization for fast & robust noise predictions of aircraft engines.

## Existing Background

- Porous material is modeled as a fluid with freq. dependent properties.
- Fluid 1 and 2 are governed by Helmholtz equation.



One parameter – **Miki model** used to estimate the fluid properties in the porous material [2].

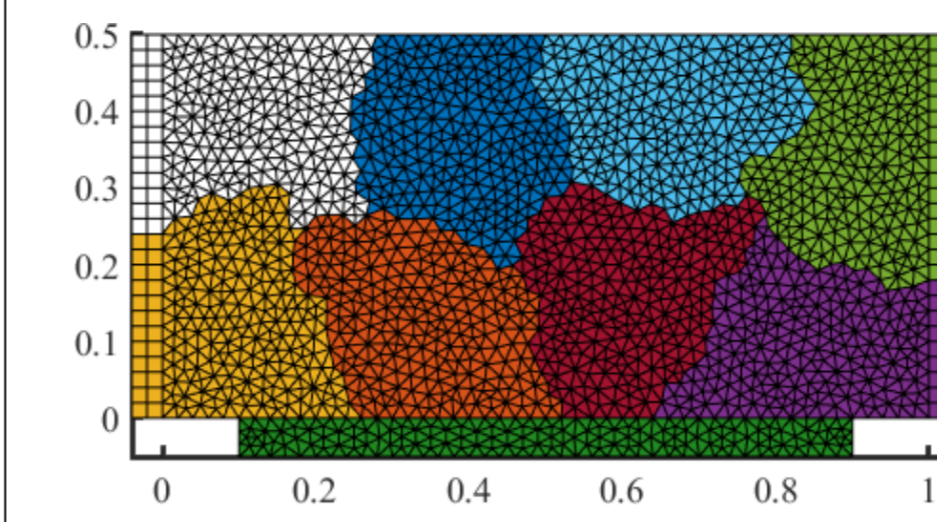


The discretization of the initial problem leads to an algebraic system of equation:

$$\mathbf{K} \mathbf{u} = \mathbf{b} \text{ where } \mathbf{K} = \tilde{\mathbf{K}} - \omega^2 \mathbf{M}$$

- For large problems, quite challenging to solve the system of equations.
- **FETI-2LM** (Finite Element Tearing and Interconnect) and **FETI-H** are used for modeling heterogeneous Helmholtz equation.

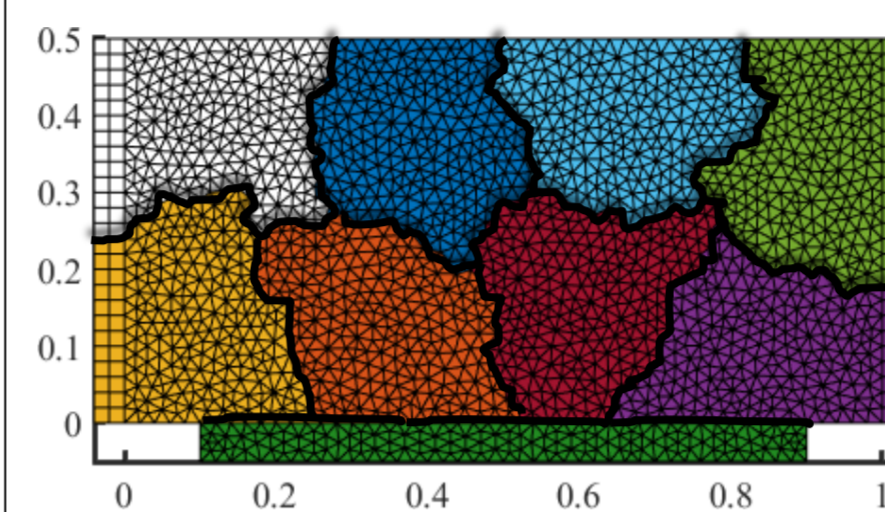
## Methodology



This system is transformed into smaller subdomain problems using FETI.

$$\mathbf{K}^n \mathbf{u}^n = \mathbf{b}^n + \boldsymbol{\lambda},$$

where n is the no. of subdomains



$\mathbf{F}_I \boldsymbol{\lambda} = \mathbf{d}$ , where  $\boldsymbol{\lambda}$  is a vector of dofs on the partitioned interfaces. This interface problem is solved iteratively using **GMRES** or **ORTHODIR** [3].

### Proposed workflow at each frequency

Select design parameters  $\phi, d$  (liner depth)

Save the LU factors (if first iteration) otherwise reuse them from the previous FEM calculation

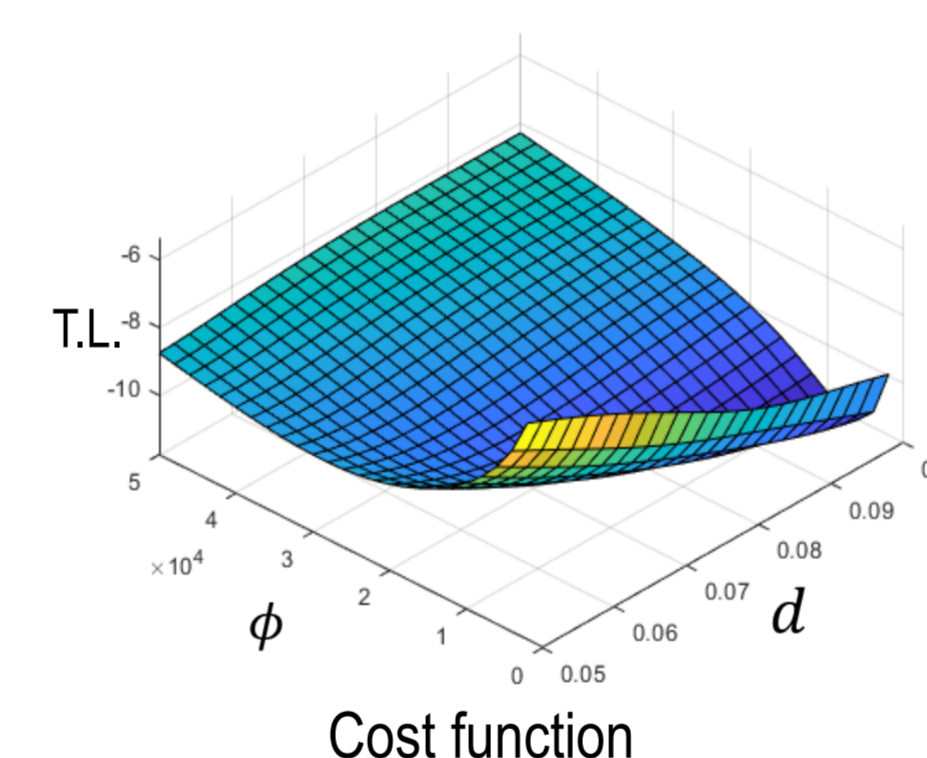
Solve the interface matrix iteratively for a given tolerance (Recycle the Krylov subspace)

Compute the transmission loss for the design parameters chosen

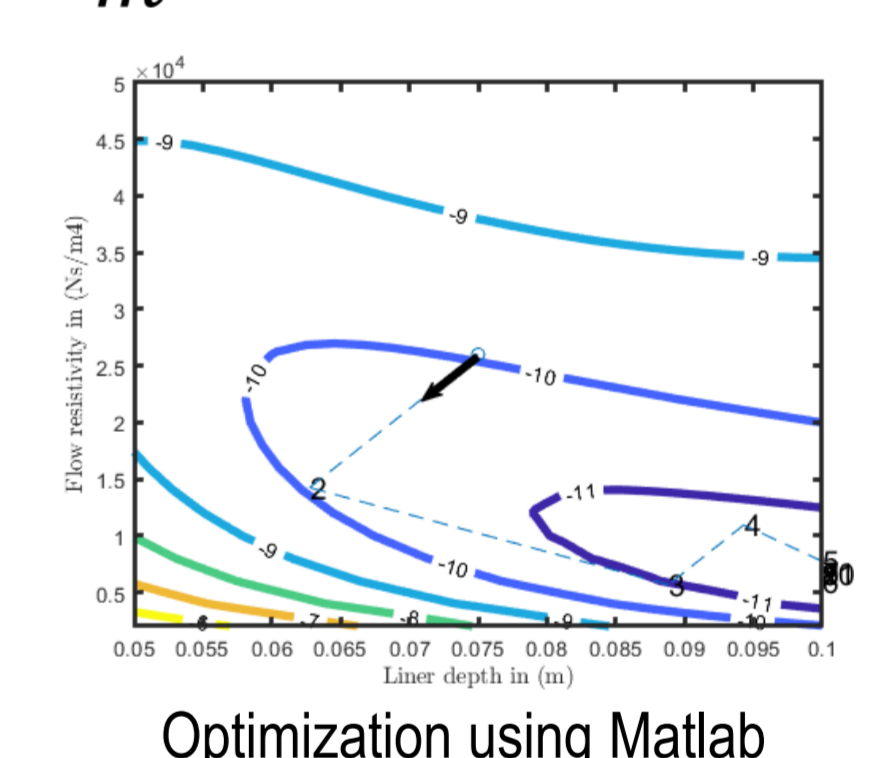
**Has to be run 100's of times in the optimization loop.**

## Preliminary Results

- The proposed workflow has been implemented and verified.
- Optimization Results for 1kHz, mode order =1.
- Range of design variables :  $\phi = 2e^3 - 5e^4 \frac{Ns}{m^4}$ ,  $d = 5 - 10 \text{ cm}$ .



Maximize T.L.



- The initial factorization reduce the CPU costs drastically.
- The Krylov subspace recycling reduces iteration count by ~50% in each optimization cycle. (except for the first cycle.)

## Expected Outcome

- **An efficient, scalable, robust, easy to use**, implementation of the proposed workflow for liner optimization.
- **Generic tool** which can be easily extended for liner optimization in automotive, commercial and domestic sectors.

## References

- [1] G. Gabard et al. "Adaptive, High-Order Finite-Element Method for Convected Acoustics". AIAA Journal, Vol. 56, No. 8 (2018), pp. 3179-3191.
- [2] Jean Allard and Nouredine Atalla. "Propagation of sound in porous media: modelling sound absorbing materials 2e". John Wiley & Sons, 2009, pp. 73-74.
- [3] Armel de La Bourdonnaye et al. "A Non-Overlapping Domain Decomposition Method for the Exterior Helmholtz Problem". In: Contemporary Mathematics 218 (1998), pp. 42-66.



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